

FIG

FIG WORKING WEEK 2017

Helsinki Finland

29 May - 2 June 2017

Presented at the FIG Working Week 2017,
May 29 - June 2, 2017 in Helsinki, Finland

Determinability of the Changes in East-West and North-South Directions with GNSS Technique

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INTRODUCTION



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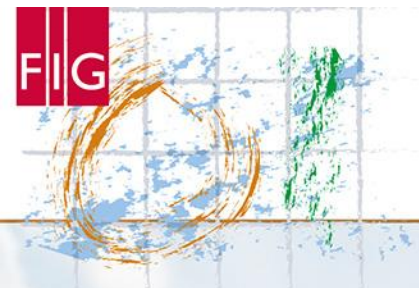


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- Nowadays, GPS (**G**lobal **P**ositioning **S**ystem), GLONASS (**G**LObal'naya **N**avigatsionnaya **S**putnikovaya **S**istema (Global Navigation Satellite System)), GALILEO, BEIDOU and other independent positioning systems, which are developed by different countries, become indispensable tools to determine point positions.
- Compared to classical techniques, GNSS techniques improve measurement accuracy, productivity and monitoring capacity
- Relative positioning methods are commonly used in geodetic applications. Geodetic networks, which have high accuracy can be established by using these methods.



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STATIC RELATIVE POSITIONING



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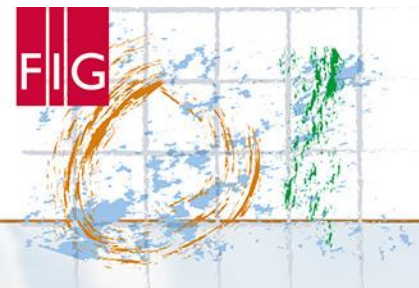


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- The GNSS technique has been a widely used method since the end of the 1980s.
- While point coordinates can be determined by using post process with GNSS technique at the beginning, in recent times these coordinates can be also determined in real time.
- With post process, the point coordinates can be determined by different methods. These methods are static positioning, rapid static positioning and pseudokinematic positioning.
- In applications requiring high accuracy, such as deformation measurements, tectonic plate movements, monitoring of large engineering constructions, the static positioning method is preferred because of the high accuracy.



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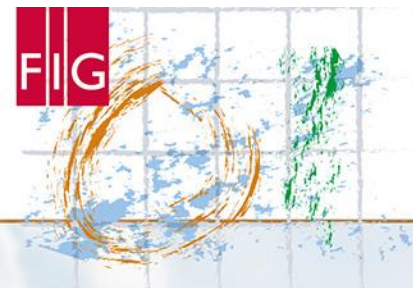


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- Accuracies for relative positioning

Mode	Horizontal accuracy
Static	5 mm + 0.5 ppm
Kinematic	5 cm + 5 ppm



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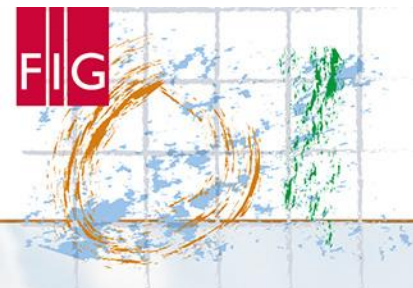


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STUDY AREA



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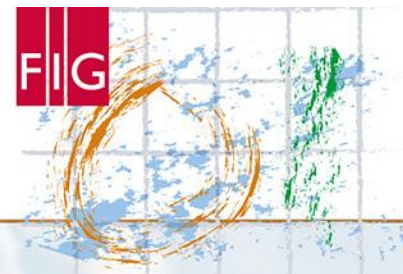


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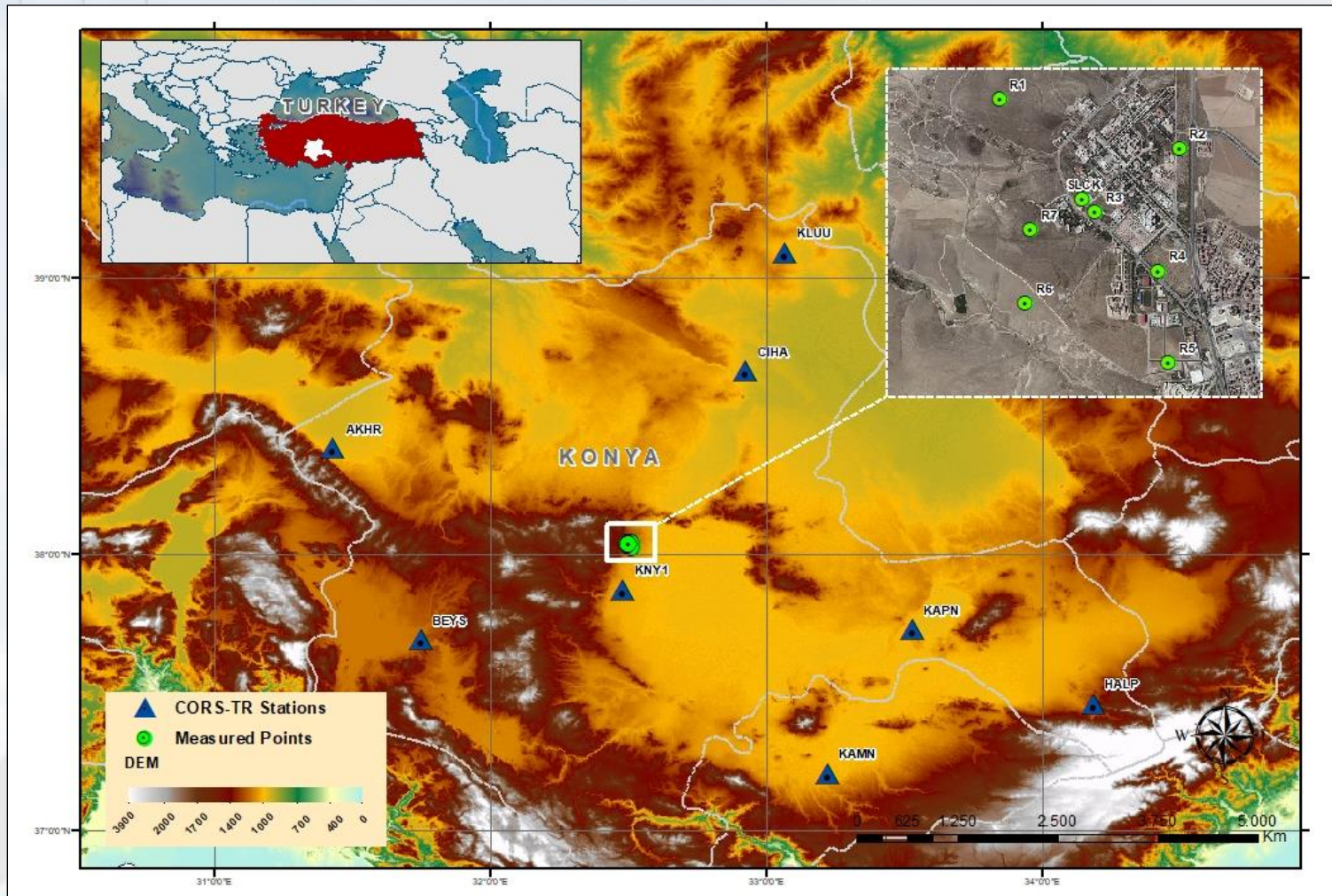




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INTRODUCTION OF MECHANISM



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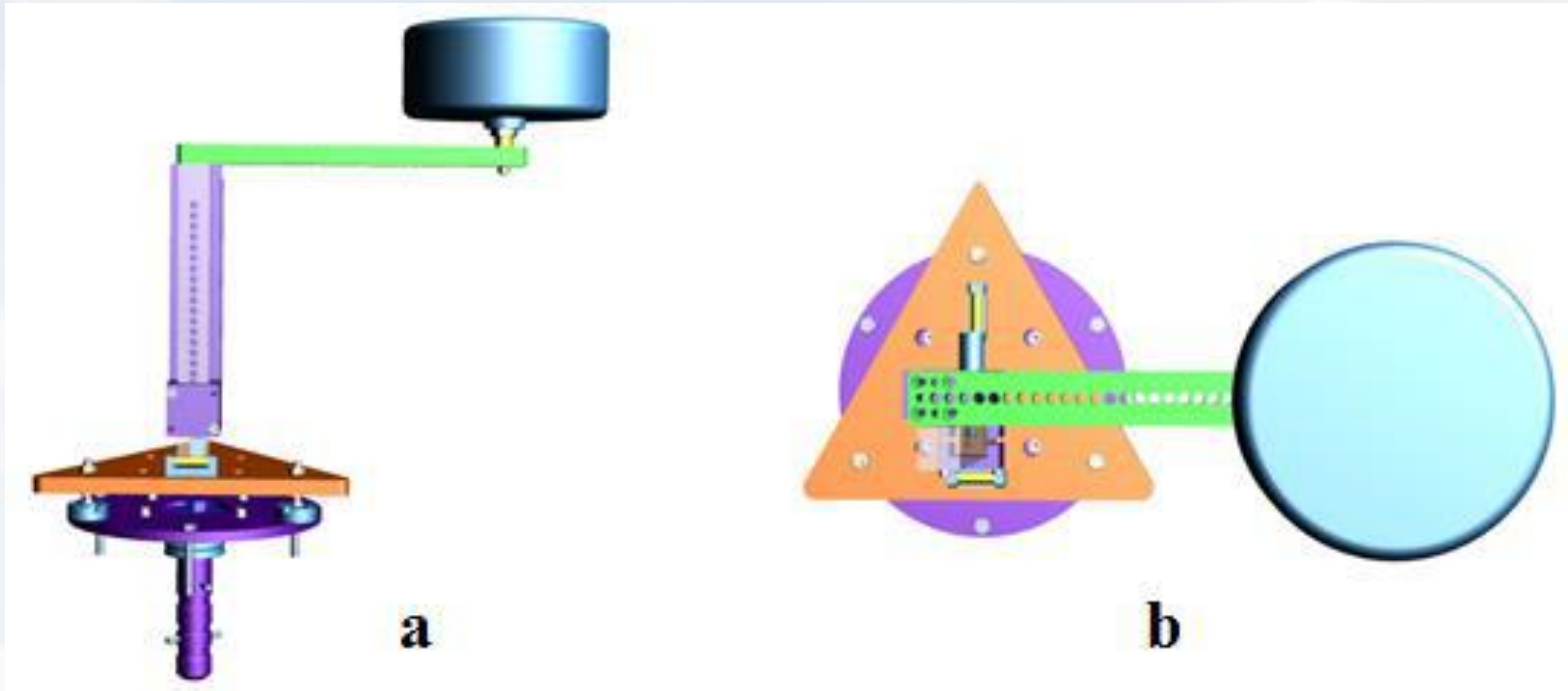


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- The view of mechanism from side (a) and top (b)

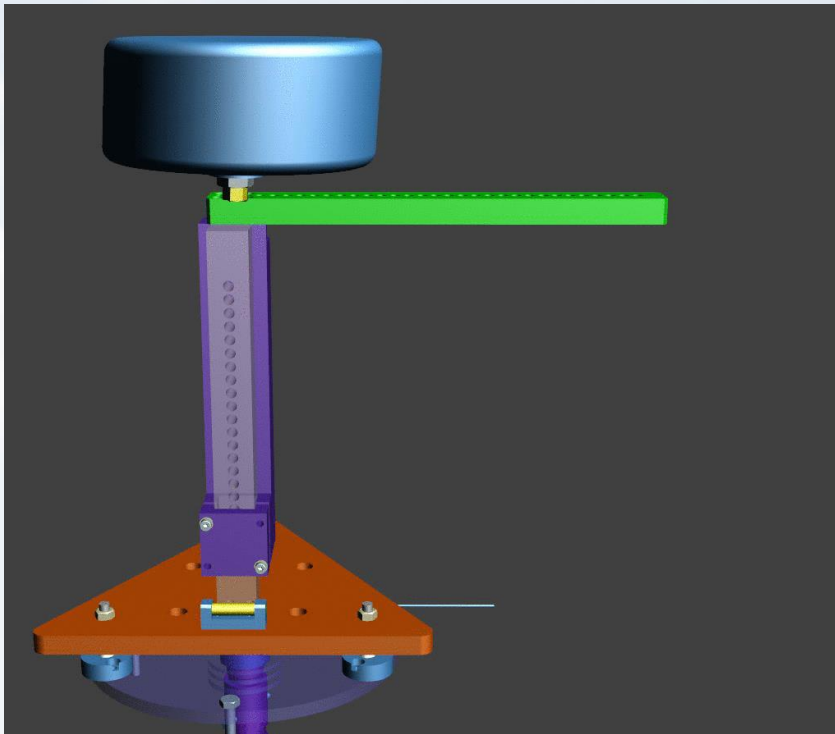


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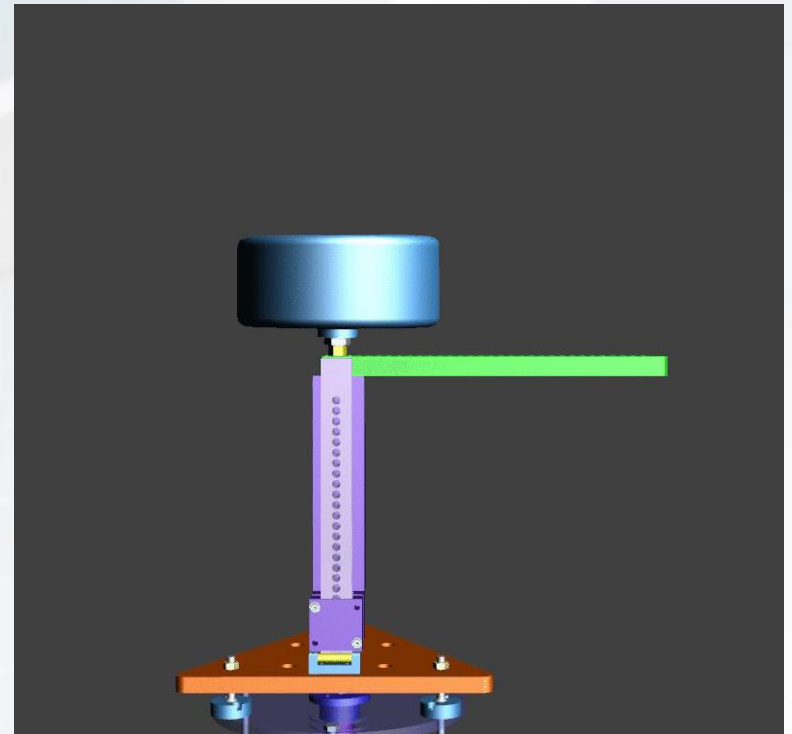
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a



b



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a



b

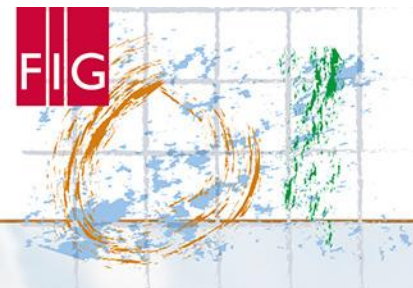


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MEASUREMENTS AND EVALUATION



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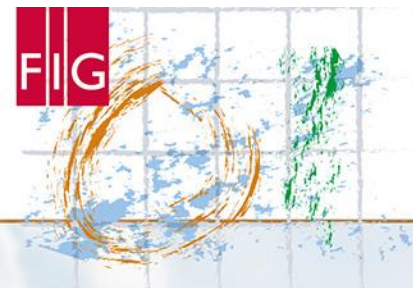


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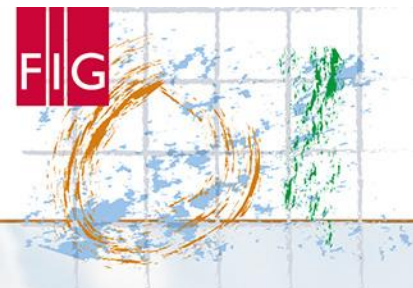


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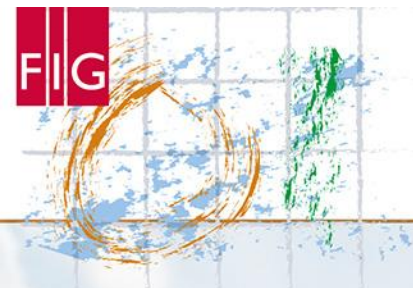


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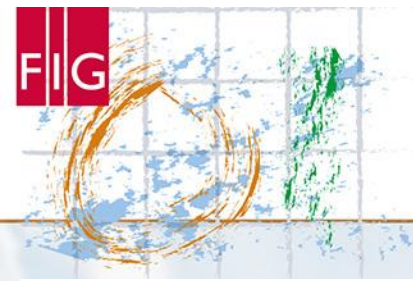
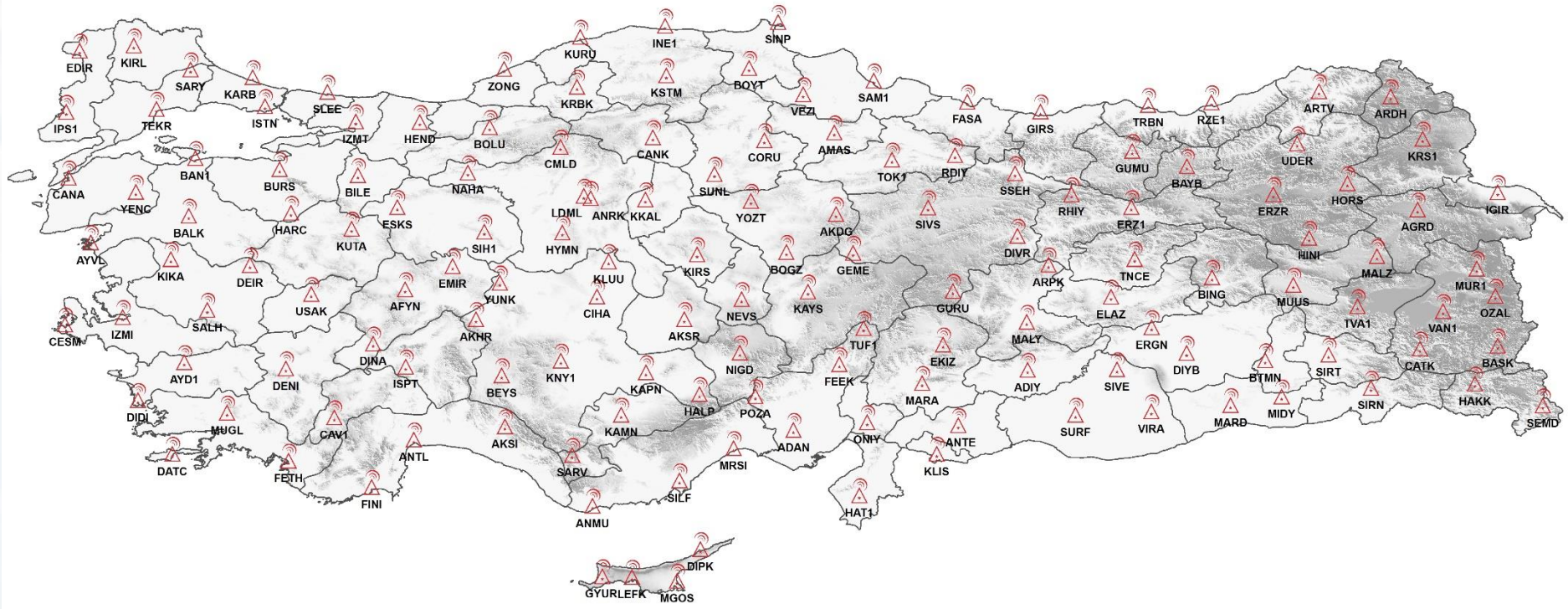


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Evaluation in the North direction

Points	dx (mm)	dy (mm)	m _{dx} (mm)	m _{dy} (mm)
0 - 1	12.2	-0.2	±3.8	±2.9
1 - 2	9.1	0.4	±3.5	±2.9
2 - 3	9.8	0.2	±3.1	±2.7
3 - 4	11.7	-1.1	±3.1	±2.8
4 - 5	11.0	0.1	±3.7	±3.2
5 - 6	11.4	0.5	±3.8	±3.2
6 - 7	7.2	-0.4	±3.2	±2.7
7 - 8	8.7	-2.0	±3.3	±2.8
8 - 9	11.0	0.6	±3.5	±3.0
9 - 10	9.9	-0.9	±3.0	±2.8



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Evaluation in the East direction

Points	dx (mm)	dy (mm)	m _{dx} (mm)	m _{dy} (mm)
0 - 1	0.7	9.2	±2.1	±1.8
1 - 2	0.0	11.6	±2.1	±1.8
2 - 3	0.0	8.7	±2.1	±2.0
3 - 4	-1.1	9.8	±2.1	±1.9
4 - 5	1.2	10.2	±2.2	±1.8
5 - 6	2.9	7.0	±2.1	±1.9
6 - 7	3.4	9.6	±2.1	±1.8
7 - 8	-0.2	9.0	±1.9	±1.8
8 - 9	0.3	8.2	±1.9	±1.8
9 - 10	0.8	9.9	±1.8	±1.6



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North direction

East direction

d (mm)	m _{dx} (mm)	Test Value t	Result T _{table} =1.96
2.2	±3.8	0.58	t < T _{table} Differences are not significant.
-0.9	±3.5	0.25	
-0.2	±3.1	0.06	
1.7	±3.1	0.55	
1.0	±3.7	0.27	
1.4	±3.8	0.37	
-2.8	±3.2	0.88	
-1.3	±3.3	0.39	
1.0	±3.5	0.29	
-0.1	±3.0	0.03	

d (mm)	m _{dy} (mm)	Test Value t	Result T _{table} =1.96
-0.8	±1.8	0.43	t < T _{table} Differences are not significant.
1.6	±1.8	0.90	
-1.3	±2.0	0.65	
-0.2	±1.9	0.10	
0.2	±1.8	0.11	
-3.0	±1.9	1.57	
-0.4	±1.8	0.22	
-1.0	±1.8	0.57	
-1.8	±1.8	1.02	
-0.1	±1.6	0.06	

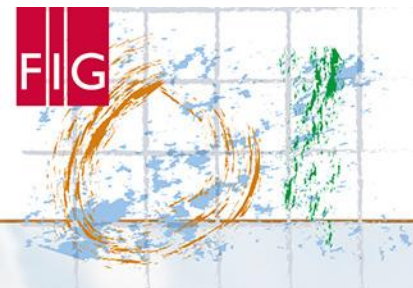
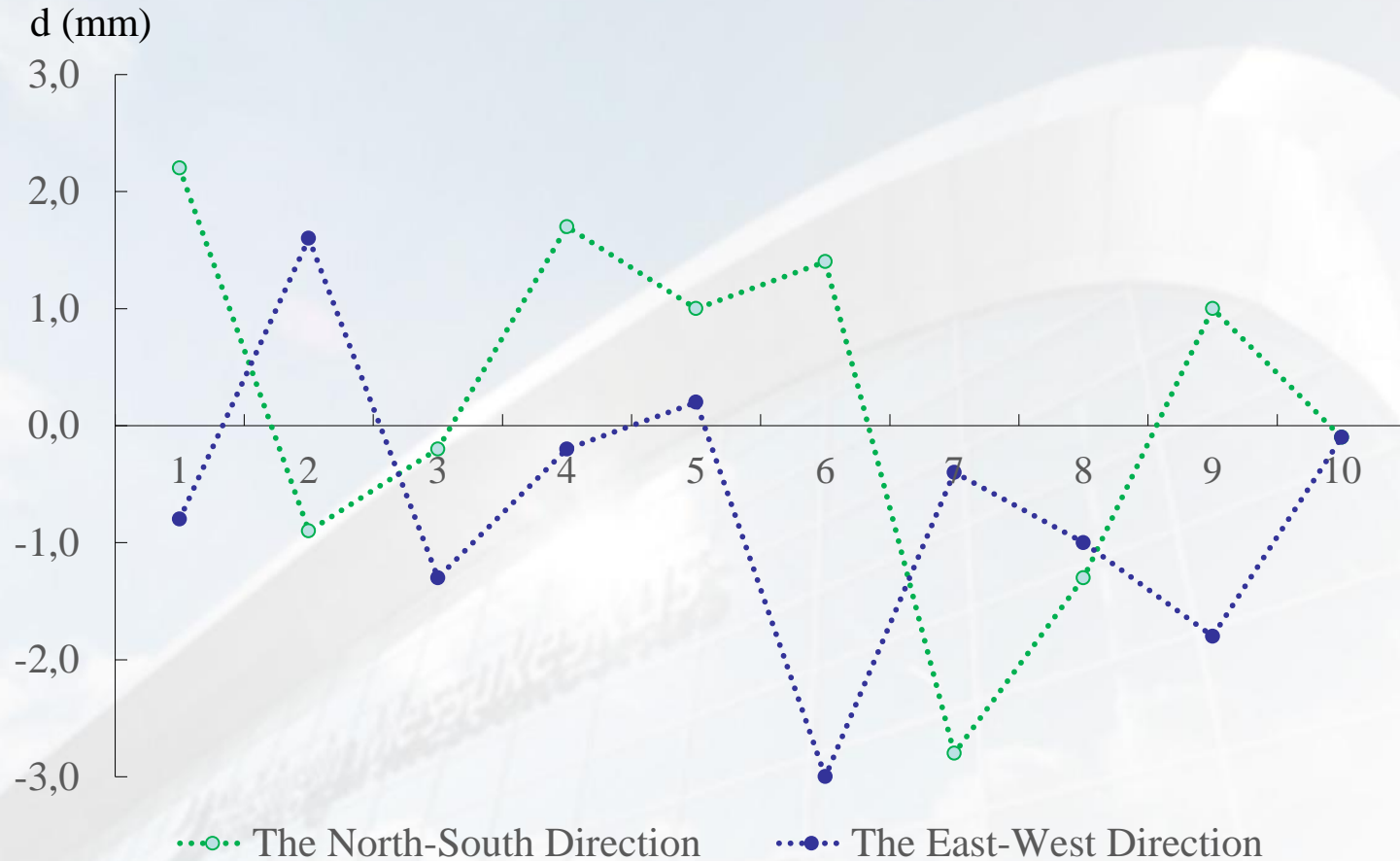


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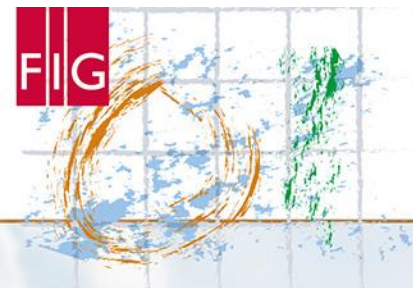


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CONCLUSION



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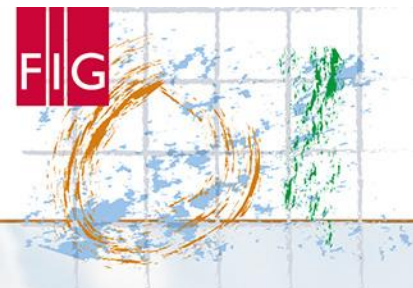


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- GNSS techniques, as well as classical terrestrial techniques, can be widely used today in determining point positions. The use of GNSS techniques is easier, faster and more economical than terrestrial techniques.
- With the help of the mechanism designed in this study, the point positions were virtually changed in the direction of the coordinate axes and the determinability of these changes was investigated. Coordinates of consecutive points were determined by the static relative positioning on the mechanism and the calculated position changes were compared with real value on the mechanism.



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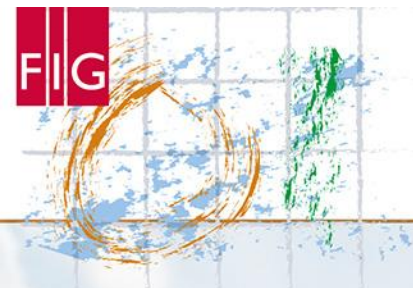


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- If it is assumed that the statistical value is 1.96, it can be seen that coordinate changes higher than 5.8 mm in the north-south direction and 3.1 mm in the east-west direction can be determined with this system. It is considered that d values and rms may vary depending on the number of reference points used, the distance of the object point to the reference points, and session durations.



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THANK YOU



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